

**Mechanics**  
**PhD Prelim Exam Spring 2020**

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**All questions have equal weighting.**

1. Consider single crystal composed of cubic Manganese, Mn. In a basis  $\{\mathbf{e}_i\}$  aligned with the crystal's cubic axes the compliance components in Voigt notation are

$$\mathbb{S} = \begin{bmatrix} 5.6 & -2.2 & -2.2 & 0 & 0 & 0 \\ -2.2 & 5.6 & -2.2 & 0 & 0 & 0 \\ -2.2 & -2.2 & 5.6 & 0 & 0 & 0 \\ 0 & 0 & 0 & 10.1 & 0 & 0 \\ 0 & 0 & 0 & 0 & 10.1 & 0 \\ 0 & 0 & 0 & 0 & 0 & 10.1 \end{bmatrix} \quad [1/\text{TPa}].$$

What is the Young's modulus for the material in the direction  $\mathbf{d} = (\mathbf{e}_1 + \mathbf{e}_2)/\sqrt{2}$ ?

2. At a given point  $\mathbf{x}_o$  in a body  $\mathcal{B}$ , the traction is known to be

$$\mathbf{t} = 1\mathbf{e}_1 + 2\mathbf{e}_2 \text{ MPa}$$

on the plane with normal  $\mathbf{n} = \mathbf{e}_1$ ; it is known to be

$$\mathbf{t} = 2\mathbf{e}_2 + 3\mathbf{e}_3 \text{ MPa}$$

on the plane with normal  $\mathbf{n} = \mathbf{e}_3$ ; and it is known to be

$$\mathbf{t} = 2/\sqrt{2}\mathbf{e}_1 + 2\mathbf{e}_2 + 5/\sqrt{2}\mathbf{e}_3 \text{ MPa}$$

on the plane with normal  $\mathbf{n} = (\mathbf{e}_2 + \mathbf{e}_3)/\sqrt{2}$ . What is the state of stress at  $\mathbf{x}_o$

3. Starting from the strong form of the equilibrium equations and assuming small strain, show that power of the external loads on a body  $\mathcal{B}$

$$\mathcal{P}_{\text{ext}} = \int_{\partial\mathcal{B}} t_i v_i dA + \int_{\mathcal{B}} b_i v_i dV$$

is equal to the stress power plus the rate of change of the kinetic energy

$$\mathcal{P}_{\text{int}} = \int_{\mathcal{B}} \left( \dot{\epsilon}_{ij} \sigma_{ij} + \frac{1}{2} \dot{\rho} v^2 \right) dV,$$

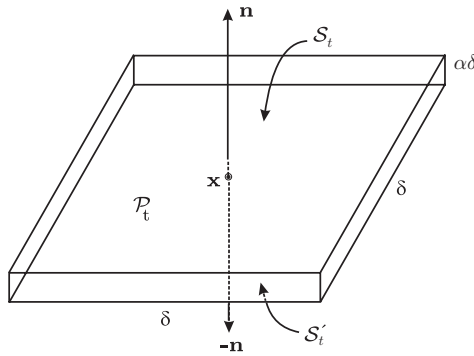
where  $v_i$  are the velocity components,  $\epsilon_{ij}$  are the small strain components,  $\sigma_{ij}$  are the stress components,  $\rho$  is the mass density,  $t_i$  are the traction components, and  $b_i$  are the volumetric body force components (force/volume). You must justify each step of your derivation with a short statement.

**Mechanics**  
**PhD Preliminary Fall 2019**

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1. Linear elastic monoclinic materials have a single plane of reflective symmetry. Show that such materials have only 13 (independent) non-zero elastic moduli.
2. Assuming only global linear and angular momentum balance, show using a *pill-box* construction, that the traction vector on a surface with normal  $\mathbf{n}$  at any point in a body  $\mathcal{B}$  is an odd function of the surface normal, i.e. show

$$\mathbf{t}(\mathbf{x}, \mathbf{n}) = -\mathbf{t}(\mathbf{x}, -\mathbf{n}) \quad \forall \mathbf{x} \in \mathcal{B}, \quad \forall \mathbf{n}. \quad (1)$$



3. Consider a bolt of diameter  $D$  and assume that the bolt is made from a linear viscoelastic material with *given* stress relaxation modulus  $E_r(t)$ . The bolt is used to join two *rigid* plates. An impact drill is used to tighten the bolt very quickly and the instantaneous force in the bolt at time  $t = 0^+$  is known to be  $P_o$ .
  - (a) Find an expression for the strain in the bolt in terms of  $P_o$  and  $E_r(\cdot)$ .
  - (b) Find an expression for the force in the bolt at any time  $t > 0$  in terms of  $E_r(\cdot)$  and your answer to Part 3a.

*Treat this problem as one-dimensional. Ignore all three-dimensional aspects of the problem.*

**Mechanics**  
**PhD Preliminary Fall 2018**

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1. (10 points) Consider the problem of small strain, isotropic, linear elasticity for two-dimensional plane strain. Show that the compatibility equation given in terms of the Airy stress function can be written as

$$\nabla^4 \phi = 0, \quad (1)$$

where in Cartesian form  $\nabla^4 \phi = \phi_{,1111} + 2\phi_{,1212} + \phi_{,2222}$ . Recall also by definition that

$$\sigma_{11} = \phi_{,22} \quad (2)$$

$$\sigma_{22} = \phi_{,11} \quad (3)$$

$$\sigma_{12} = -\phi_{,12}, \quad (4)$$

and  $\nabla \times \nabla \times \boldsymbol{\epsilon} = 0$ , which in Cartesian form is given as  $S_{pq} = e_{pki}e_{qlj}\epsilon_{ij,kl} = 0$ .

2. (10 points) For the motion

$$\boldsymbol{x} = X_1 \mathbf{e}_1 + (bX_1 + X_2) \mathbf{e}_2 + \left(X_3 + \frac{1}{2}c(X_3)^2\right) \mathbf{e}_3 \quad (5)$$

with given constants  $b$  and  $c$ , determine (i) the deformation gradient field  $\mathbf{F}(\mathbf{X})$ , (ii) the extremal stretches at the point  $(X_1, X_2, X_3) = (1, 1, 1)$ , and (iii) the volumetric strain at this point.

3. (10 points) Consider a material point whose stress state is given by

$$\boldsymbol{\sigma}(t) \sim \begin{bmatrix} 0 & a \cdot t & 0 \\ a \cdot t & 0 & 0 \\ 0 & 0 & a \cdot t \end{bmatrix}. \quad (6)$$

Assume the material to be a ductile metal governed by the Mises yield condition  $f(\boldsymbol{\sigma}) = \|\boldsymbol{\sigma}'\| - \sqrt{\frac{2}{3}}\sigma_Y$ , where  $\boldsymbol{\sigma}'$  denotes the stress deviator and  $\sigma_Y$  is the material's yield stress. (i) Find an expression for the time of initial yield; (ii) Assuming associative plastic flow (Prandtl-Reuss), determine the direction of plastic flow at the moment of yield; (iii) Can the given loading be sustained by the material if material does not harden?

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**Mechanics**  
**PhD Preliminary Spring 2017**

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1. (10 points) Consider a body  $\Omega$  that is assembled by gluing together two separate bodies along a flat interface. The normal vector to the interface is given by  $\mathbf{n} = (1 \ 1 \ 1)^T$ . Assume that  $\Omega$  is subjected to a homogeneous (Cauchy) stress field

$$\boldsymbol{\sigma} = \beta \begin{bmatrix} 1 & 2 & 3 \\ 2 & 2 & 3 \\ 3 & 3 & 3 \end{bmatrix} \text{ MPa}$$

where  $\beta$  is a non-dimensional load factor. Assume that the interface fails when the normal stress on the interface exceeds 100 MPa. Determine the maximal permissible value of  $\beta$ .

2. (10 points) Consider a small-strain hyperelastic body  $\Omega$ , free of body forces, with strain energy density  $W(\boldsymbol{\epsilon})$  subjected to dead-loads  $\bar{\mathbf{t}}$  on  $\partial\Omega_t \subset \partial\Omega$  and restrained with zero displacement on  $\partial\Omega_u \subset \partial\Omega$ , where  $\overline{\partial\Omega_t} \cap \overline{\partial\Omega_u} = \partial\Omega$ . Starting from the principle of minimum potential energy, derive the strong form of the governing equilibrium equations.
3. (10 points) A three dimensional viscoelastic body  $\Omega = \{\mathbf{x} \mid x_1^2 + x_2^2 \leq R^2 \text{ and } |x_3| \leq L/2\}$  has a measured displacement field  $\mathbf{u} = (\alpha x_1/R)\mathbf{e}_1 + (\alpha x_2/R)\mathbf{e}_2$ , where  $R$  and  $L$  are given and  $\alpha > 0$  is much smaller than  $R$  and  $L$ . Determine the algebraically maximum and minimum normal strains in the body as well as the maximum shear strain in the body.
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